

A BRIEF INTRODUCTION TO

GRTensor

on MAPLE platform



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As a part of Ph.D. course PHYS 601

TOPICS ADDRESSED:

- HISTORY OF MAPLE
- INTRODUCTION TO INTERFACE
- OPERATIONS POSSIBLE
- BENEFITS/DRAWBACKS
- TENSORS
- INTRODUCTION TO GRTensor



Toolbar

Units (SI)

Units (FPS)

Common Symbols

Matrix

Rows: 2

Columns: 2

Choose...

Type: Custom values

Shape: Any

Data type: Any

Insert Matrix

Components

Draw

Canvas Properties

Greek

Arrows

Relational

Relational Round

Negated

Large Operators

Operators

Open Face

Fraktur

Script

Miscellaneous

Workspace

A SHORT INTRODUCTION TO MAPLE

- First developed in 1980 by the Symbolic Computation Group at the University of Waterloo in Waterloo, Ontario, Canada.
- Since 1988, it has been developed and sold commercially by Waterloo Maple Inc. (also known as Maplesoft)
- 15 major versions released.
- Supports **analytical** and numerical computation and visualisation.
- Maple is based on a small kernel, written in C.

Status bar

$$y := 5x^3 + \sin(x) + \exp(-x^2);$$

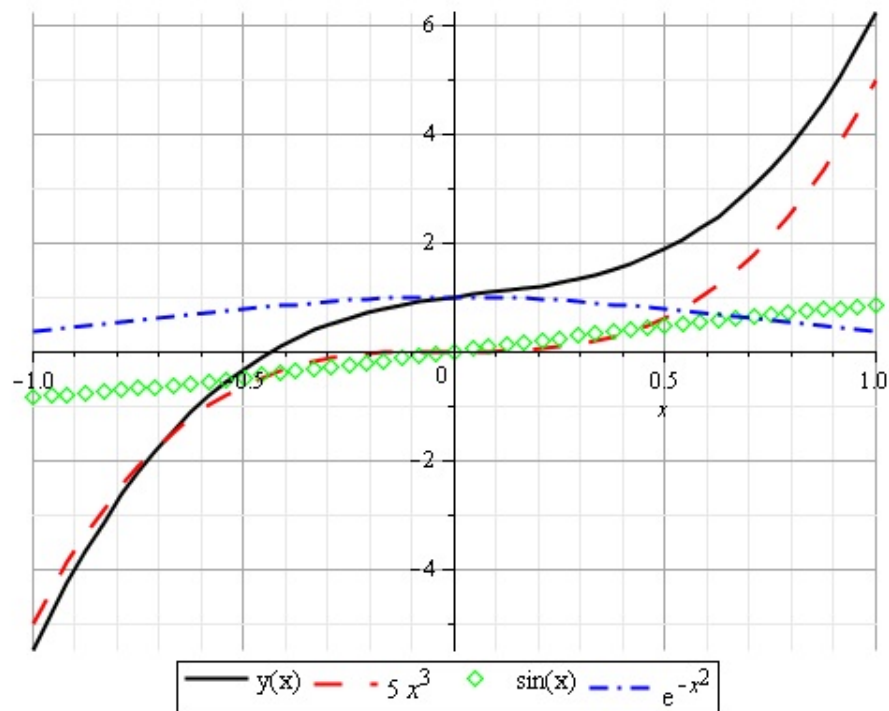
$$5x^3 + \sin(x) + e^{-x^2} \tag{1}$$

$$\text{Int}(y, x) = \text{int}(y, x);$$

$$\int (5x^3 + \sin(x) + e^{-x^2}) dx = \frac{5}{4}x^4 - \cos(x) + \frac{1}{2}\sqrt{\pi} \text{erf}(x) \tag{2}$$

$$\text{plot}([y, 5x^3, \sin(x), \exp(-x^2)], x = -1 .. 1);$$

2-D PLOT ILLUSTRATION



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`ode := diff(y(x), x, x) = 2*y(x) + 1;`

$$\frac{d^2}{dx^2} y(x) = 2y(x) + 1 \quad \leftarrow \text{O.D.E.} \quad (1)$$

`dsolve(ode);`

$$y(x) = e^{\sqrt{2}x} _C2 + e^{-\sqrt{2}x} _C1 - \frac{1}{2} \quad \leftarrow \text{Analytic soln.} \quad (2)$$

`ics := y(0) = 1, D(y)(0) = 0;`

$$y(0) = 1, D(y)(0) = 0 \quad \leftarrow \text{Initial cond.} \quad (3)$$

`dsolve({ode, ics});`

$$y(x) = \frac{3}{4} e^{\sqrt{2}x} + \frac{3}{4} e^{-\sqrt{2}x} - \frac{1}{2} \quad (4)$$

`sol := dsolve({ode, ics}, y(x), method = laplace);`

$$y(x) = -\frac{1}{2} + \frac{3}{2} \cosh(\sqrt{2}x) \quad \leftarrow \text{Laplace mthd.} \quad (5)$$

`series_sol := dsolve({ode, ics}, y(x), series);`

$$y(x) = 1 + \frac{3}{2} x^2 + \frac{1}{4} x^4 + O(x^6) \quad \leftarrow \text{Series soln.} \quad (6)$$

Expression

Units (SI)

Units (FPS)

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Canvas Properties

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Relational Round

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Text **Math** 2D Math Times New Roman 12 **B** **I** **U** [List icons]

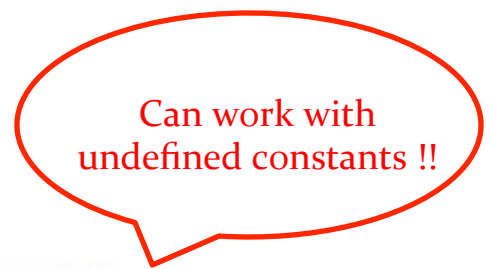
```
f := sin(x + y) - exp(x) * y = 0;
g := x^2 - y = 2;
fsolve( {f, g} );
```

$$\begin{aligned} \sin(x + y) - e^x y &= 0 \\ x^2 - y &= 2 \\ \{x = -6.017327250, y = 34.20822723\} \end{aligned} \tag{1}$$

restart;

```
solve( {a*x + b*y = c, d*x + e*y = f}, [x, y]);
```

$$\left[\left[x = -\frac{-ec + fb}{-db + ae}, y = \frac{-dc + af}{-db + ae} \right] \right] \tag{2}$$





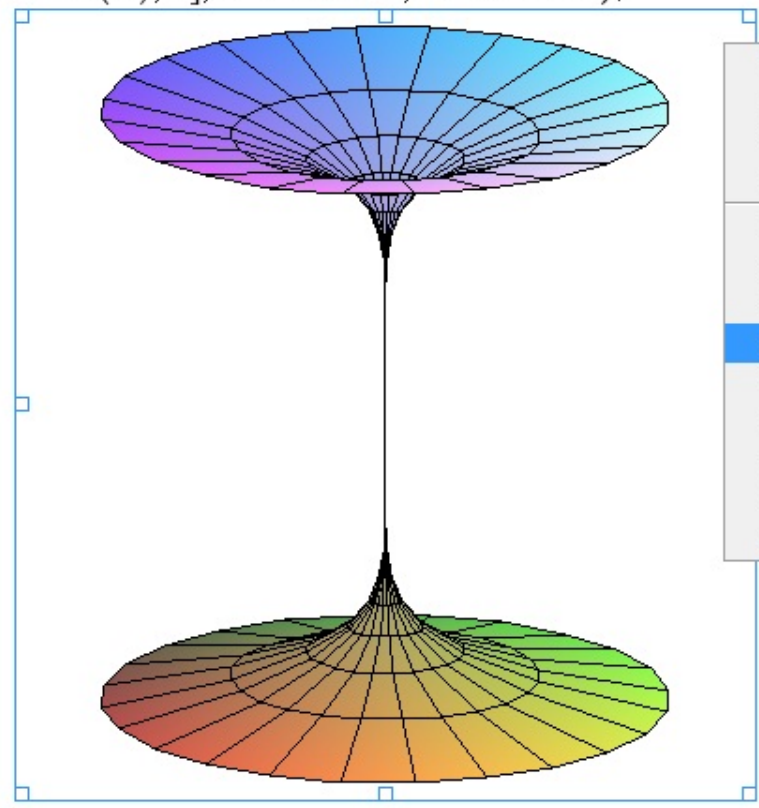
- ▶ Favorites
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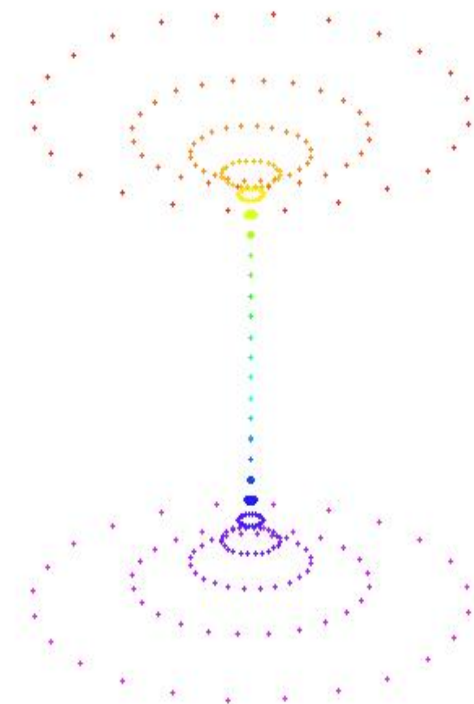
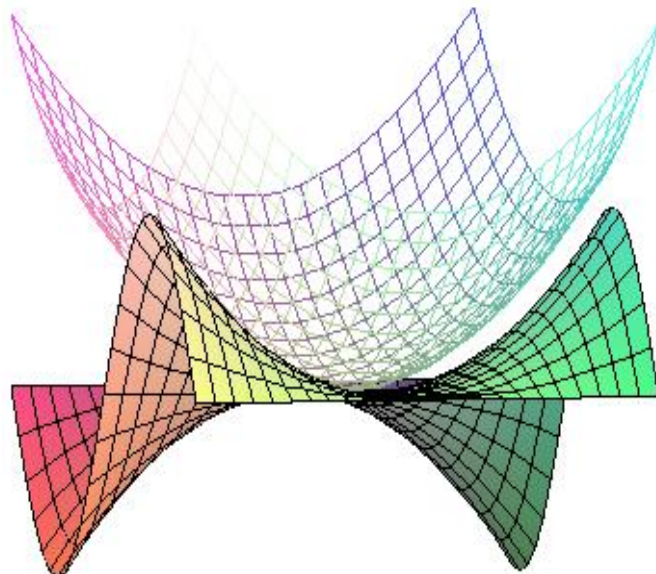
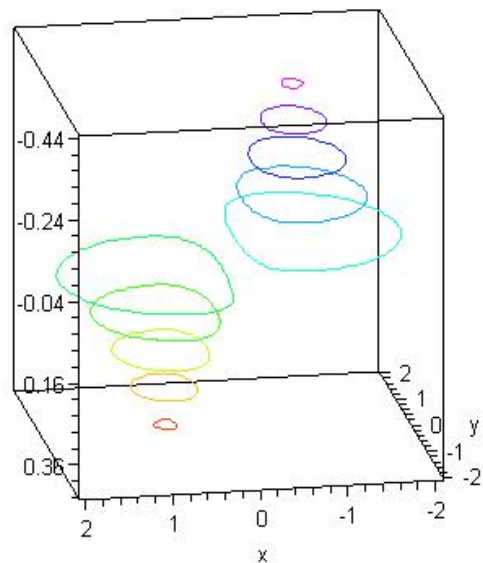
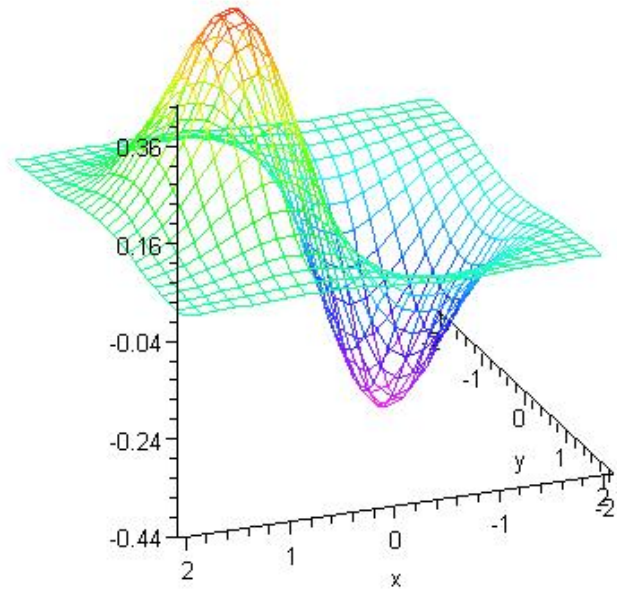
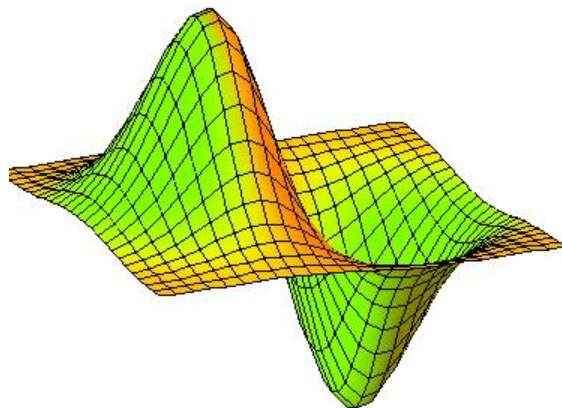
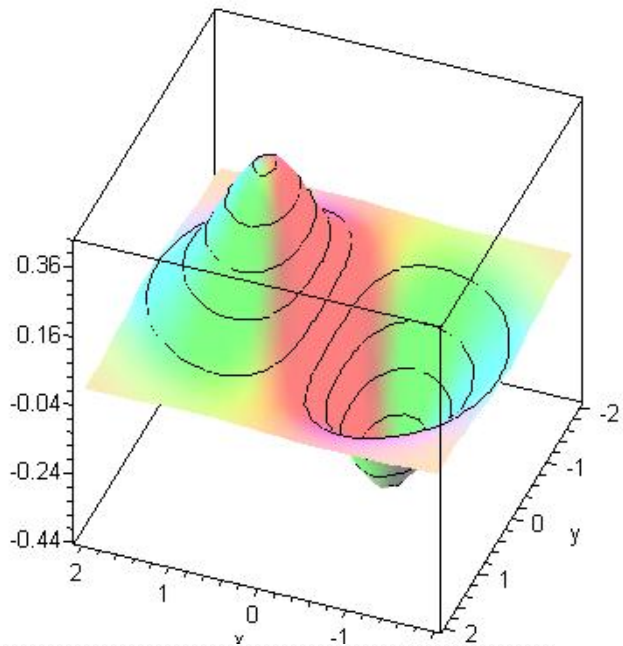
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360° view

↑
plot formatting options

```
plot3d([t^7*sin(u), t^7*cos(u), t], t=-20..20, u=0..2 Pi);
```



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- Copy Ctrl+C
- Copy full precision
- Paste Ctrl+V
- Style ▶
- Color ▶
- Lighting ▶
- Axes** ▶
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 - Mode...
 - Range...
- Scaling Constrained
- Projection...
- Transparency...
- Manipulator ▶
- Export ▶



TENSORS

- An incomplete definition
- Tensors generally used in cosmology
- How are they obtained
- Need for a package like GRTensor



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*schw.mw *newmetric.mw *kerr2.mw

Text **Math** 2D Output Times New Roman 12 B I U

Line element

Kerr Metric

$$ds^2 = \frac{(r^2 + a^2 \cos(\theta)^2) dr^2}{r^2 - 2mr + a^2} + (r^2 + a^2 \cos(\theta)^2) d\theta^2 + \sin(\theta)^2 \left(r^2 + a^2 + \frac{2mr a^2 \sin(\theta)^2}{r^2 + a^2 \cos(\theta)^2} \right) d\phi^2 - \frac{4mar \sin(\theta)^2 d\phi dt}{r^2 + a^2 \cos(\theta)^2} + \left(-1 + \frac{2mr}{r^2 + a^2 \cos(\theta)^2} \right) dt^2 \tag{1}$$

$$R_{r\phi r\phi} = \left((-14a^6 \cos(\theta)^4 m r^4 + 11a^6 r^5 \sin(\theta)^2 \cos(\theta)^2 + 10a^6 r^5 \cos(\theta)^4 \sin(\theta)^2 - 2a^6 r^4 \cos(\theta)^6 m - 7a^4 r^7 \sin(\theta)^2 - 41a^6 m r^4 \sin(\theta)^2 \cos(\theta)^2 + 2a^8 \cos(\theta)^2 r^3 \sin(\theta)^4 - 6a^2 r^9 \sin(\theta)^2 + a^8 r^3 \cos(\theta)^8 + a^2 r^9 + 16a^6 r^4 m \sin(\theta)^4 \cos(\theta)^2 + 7a^8 \cos(\theta)^4 m r^2 \sin(\theta)^4 + 3a^8 r^2 \cos(\theta)^6 m \sin(\theta)^2 + 2r^{10} m - 3a^6 r^5 \sin(\theta)^2 - r^{11} - 2a^2 r^8 m + 3a^{10} r \cos(\theta)^8 + a^{10} m \sin(\theta)^2 \cos(\theta)^6 - a^{10} \cos(\theta)^4 m \sin(\theta)^2 + 7a^{10} \cos(\theta)^4 r \sin(\theta)^2 + 2a^{10} \cos(\theta)^4 r \sin(\theta)^4 + a^{10} \cos(\theta)^4 m \sin(\theta)^4 - 6a^8 \cos(\theta)^6 m r^2 + 3a^8 r^3 \cos(\theta)^6 \sin(\theta)^2 + 23a^8 r^3 \sin(\theta)^2 \cos(\theta)^4 + 2a^8 \cos(\theta)^4 r^3 \sin(\theta)^4 + 4a^8 \cos(\theta)^2 r^3 \sin(\theta)^2 + 2a^6 r^5 \cos(\theta)^6 + 10a^8 \cos(\theta)^6 r^3 - 2a^2 r^9 \cos(\theta)^2 + 6a^4 \cos(\theta)^2 r^7 + 12a^6 \cos(\theta)^4 r^5 + 24a^4 m^2 r^5 \sin(\theta)^2 \cos(\theta)^2 - 10a^6 r^4 \cos(\theta)^4 m \sin(\theta)^2 - 15a^4 r^6 \cos(\theta)^2 m \sin(\theta)^2 + 2a^6 \cos(\theta)^2 r^5 \sin(\theta)^4 - 5a^6 r^4 m \sin(\theta)^4 + 5a^6 m r^4 \sin(\theta)^2 - 2a^4 r^6 \cos(\theta)^4 m + a^4 r^7 \cos(\theta)^2 \sin(\theta)^2 - 10a^4 \cos(\theta)^2 r^6 m + 5a^{10} \cos(\theta)^6 r \sin(\theta)^2 - 8a^4 m^2 r^5 \sin(\theta)^2 + 13a^4 m r^6 \sin(\theta)^2 + 8a^4 r^5 m^2 \sin(\theta)^4 - 3a^4 r^6 m \sin(\theta)^4 + 2a^2 r^8 m \cos(\theta)^2 + 14a^2 r^8 m \sin(\theta)^2 - 8a^2 m^2 r^7 \sin(\theta)^2 - 21a^8 m \sin(\theta)^2 \cos(\theta)^4 r^2 - 12a^8 \cos(\theta)^2 m r^2 \sin(\theta)^2 + 8a^8 \cos(\theta)^2 m r^2 \sin(\theta)^4 + 4a^8 \cos(\theta)^2 m r^2 \sin(\theta)^6 + 24a^6 \cos(\theta)^2 m^2 \sin(\theta)^2 r^3 - 24a^6 \cos(\theta)^2 m^2 \sin(\theta)^4 r^3) m \sin(\theta)^2 \right) / \left((a^4 \cos(\theta)^2 + r^2 a^2 \cos(\theta)^2 - 2a^2 m r + a^2 r^2 + 2m r a^2 \sin(\theta)^2 + r^4 - 2r^3 m) (r^2 - 2m r + a^2) (r^2 + a^2 \cos(\theta)^2)^3 \right) \tag{2}$$



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```

gcalc(Chr(up, dn, dn)) :
Created definition for Chr(up, dn, dn)
Calculated detg for schw (0.000000 sec.)
Calculated g(up, up) for schw (0.016000 sec.)
Calculated g(dn, dn, pdn) for schw (0.000000 sec.)
Calculated Chr(dn, dn, dn) for schw (0.015000 sec.)
Calculated Chr(up, dn, dn) for schw (0.000000 sec.)
    
```

Calculating christoffel's symbols

CPU Time = 0.109

(3)

gdisplay(Chr(up, dn, dn)) :

Display the result

For the schw spacetime:

$$Chr(up, dn, dn)$$

$$\Gamma^r_{rr} = -\frac{m}{(r-2m)r}$$

$$\Gamma^\theta_{\theta r} = -\frac{1}{r}$$

$$\Gamma^\phi_{\phi r} = -\frac{1}{r}$$

$$\Gamma^t_{tr} = -\frac{m}{(r-2m)r}$$

$$\Gamma^\theta_{r\theta} = \frac{1}{r}$$

$$\Gamma^r_{\theta\theta} = r - 2m$$

$$\Gamma^\phi_{\dots} = -\frac{\cos(\theta)}{\dots}$$



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 ψ ω
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Default spacetime = newmetric

For the newmetric spacetime:

Coordinates

$x(up)$

$$x^a = [t \ r \ \theta \ \phi]$$

Line element

$$ds^2 = -dt^2 + dr^2 + ([r]^2 - c^2[t]^2) d\theta^2 + d\phi^2 \leftarrow \text{The new metric}$$

`makeg()` completed.

`qload(newmetric)`:

Default metric is now newmetric.

`grcalc(Chr(up, dn, dn))`:

`grdisplay(Chr(up, dn, dn))`:

For the newmetric spacetime:

Chr(up, dn, dn)

$$\Gamma^{\theta}_{\theta t} = -\frac{c^2 [t] [1]}{-[r]^2 + c^2 [t]^2}$$

$$\Gamma^{\theta}_{\theta r} = \frac{[r] [1]}{-[r]^2 + c^2 [t]^2}$$

$$\Gamma^{\theta}_{t\theta} = \frac{c^2 [t] [1]}{-[r]^2 + c^2 [t]^2}$$

$$\Gamma^{\theta}_{r\theta} = -\frac{[r] [1]}{-[r]^2 + c^2 [t]^2}$$

$$\Gamma^t_{\theta\theta} = c^2 [t] [1]$$

$$\Gamma^r = [r] [1]$$

SYNTAX	RESULT
$R(dn, dn, pdn)$	$R_{ab,c}$
$R(dn, d, cdn)$	$R_{ab;c}$
> grdef ('A{a b}'):	Creates a new vector 'A _{ab} '
> grcalc (A(dn,dn)):	Inputs the components of 'A _{ab} '
> grdef ('A{^a ^b}'):	Creates a new vector 'A ^{ab} '
> grdef ('new object:= object definition')	Defines a new tensor
$R\{^a ^b b c\}$	ΣR^{ab}_{bc}
$R\{^a ^b\} * \text{Box}[R\{ a b \}]$	$R^{ab} \square R_{ab}$

Some other jobs GRTensor can be used for :

- **Defining new tensors**
- **Modifying tensor components**
- **Finding sum / products of tensors**
- **Tensor Calculus**
- **Simplifying the results**
- **Working in multiple geometries**
- **Many other operations I am still unaware of.....**